# Diameter and connectivity of 3-arc graphs

Martin Knor<sup>1</sup> and Sanming Zhou<sup>2</sup>

 <sup>1</sup> Department of Mathematics
Faculty of Civil Engineering, Slovak University of Technology Radlinského 11, 813 68 Bratislava, Slovakia E-mail: knor@math.sk
<sup>2</sup> Department of Mathematics and Statistics The University of Melbourne Parkville, VIC 3010, Australia E-mail: smzhou@ms.unimelb.edu.au

#### Abstract

An arc of a graph is an oriented edge and a 3-arc is a 4-tuple (v, u, x, y) of vertices such that both (v, u, x) and (u, x, y) are paths of length two. The 3-arc graph of a given graph G, X(G), is defined to have vertices the arcs of G. Two arcs uv, xy are adjacent in X(G)if and only if (v, u, x, y) is a 3-arc of G. This notion was introduced in recent studies of arc-transitive graphs. In this paper we study diameter and connectivity of 3-arc graphs. In particular, we obtain sharp bounds for the diameter and connectivity of X(G) in terms of the corresponding invariant of G.

This is a preprint of an article accepted for publication in Discrete Mathematics ©2010 (copyright owner as specified in the fournal).

Key words: 3-arc graph, diameter, connectivity, splitting construction, 3-arc graph construction

AMS subject classification (2000): 05C12, 05C40

## 1 Introduction

In this paper we study a new graph operator, namely the 3-arc graph construction which was first introduced [11, 16] in studying those arc-transitive graphs whose automorphism group contains a subgroup acting imprimitively on the vertex set. (A graph is arc-transitive if its automorphism group is transitive on the set of oriented edges.) This construction has been proved to be very useful in classifying or characterizing [11] certain families of arc-transitive graphs. For example, the cross-ratio graphs in [5] can be defined [15] equivalently as 3-arc graphs of ( $\Gamma$ , 2)arc transitive complete graphs, where  $\Gamma$  is a 3-transitive subgroup of P $\Gamma$ L(2, q), and the main result in [17] relies heavily on this construction as well. In two recent papers [7, 12] the 3-arc graph construction has also been used to construct some families of arc-transitive graphs. In this paper we will investigate this construction from a pure combinatorial point of view without involving arc-transitivity with focus on diameter and connectivity.

Let G be a graph. An arc of G is an ordered pair of adjacent vertices. For adjacent vertices u, v of G, we use uv to denote the arc from u to v,  $vu \ (\neq uv)$  the arc from v to u, and  $\{u, v\}$  the edge between u and v. A 3-arc of G is a 4-tuple (v, u, x, y) of vertices of G such that both

v, u, x and u, x, y are paths of length two. It is allowed to have v = y, and in this case the 3-arc (v, u, x, y) becomes the oriented cycle (v, u, x, v) of length three. A set  $\Delta$  of 3-arcs of G is said to be *self-paired* if  $(v, u, x, y) \in \Delta$  implies  $(y, x, u, v) \in \Delta$ .

**Definition 1** Let G be a graph and  $\Delta$  a self-paired set of 3-arcs of G. The 3-arc graph [11, 16] of G with respect to  $\Delta$ ,  $X(G, \Delta)$ , is defined to have vertex set the set of arcs of G such that two vertices corresponding to two arcs uv, xy are adjacent if and only if  $(v, u, x, y) \in \Delta$ . The edge of  $X(G, \Delta)$  between uv and xy will be denoted by  $\{uv, xy\}$ .

In the case when  $\Delta$  is the set of all 3-arcs of G, the corresponding graph  $X(G, \Delta)$  is called the 3-arc graph of G, denoted by X(G).

Since  $\Delta$  is self-paired,  $X(G, \Delta)$  is an undirected graph. In particular, X(G) is an undirected graph with 2|E(G)| vertices and  $\sum_{\{u,x\}\in E(G)} (\deg_G(u) - 1)(\deg_G(x) - 1))$  edges.

We can view X as a graph operator which outputs the 3-arc graph X(G) for any given G. This operator is closely related to the well known line graph operator L. In fact, we can obtain X(G) from the line graph L(G) of G by the following operations. First, we split each vertex  $\{u, v\}$  of L(G) (that is, an edge of G) into two vertices, namely uv and vu. Then, for any two vertices  $\{u, v\}, \{x, y\}$  of L(G) which are distance two apart in L(G), say, u and x are adjacent in G, we join uv and xy by an edge. The graph obtained this way is isomorphic to X(G). On the other hand, define  $P\{u,v\} = \{uv,vu\}$  for each vertex  $\{u,v\}$  of L(G), and let  $\mathcal{P} = \{P\{u, v\} : \{u, v\} \in E(G)\}$ . Then  $\mathcal{P}$  is a partition of the vertex set of X(G) into parts of size two, and the quotient graph of X(G) with respect to  $\mathcal{P}$  is isomorphic to the graph obtained from the square of L(G) by deleting the edges of L(G). (The square of a graph is defined to have the same vertex set in which two vertices are adjacent if and only if their distance in the original graph is one or two.) Obviously, there is a bijection between the edges of X(G) and those of the 2-path graph  $P_2(G)$ , which is defined to have vertices the paths of length two in G such that two vertices are adjacent if and only if the union of the corresponding paths is a path or a cycle of length three, see [4]. Since  $P_2(G)$  is a spanning subgraph of the second iterated line graph  $L^2(G) = L(L(G))$  (see e.g. [8]), we have yet another relation between 3-arc graphs and line graphs.

There is an extensive literature on line graphs. See for example [6, 14] for surveys and [13, 9] for diameter and connectivity of iterated line graphs respectively. Some results on diameter of path graphs can be found in [2], while the connectivity of  $P_2$ -path graphs is studied e.g. in [10] and [1]. In contrast, we know little about the 3-arc graph operator X, despite its usefulness in algebraic graph theory. In this paper we will focus on diameter and connectivity of 3-arc graphs.

Obviously, adding or deleting isolated vertices does not affect X(G). Moreover, if G contains two connected components other than isolated vertices, then X(G) is a disconnected graph; if G contains a degree-one vertex, say, u, which is adjacent to v, then uv is an isolated vertex of X(G). Therefore, we will consider only connected graphs G with minimum degree  $\delta(G) \geq 2$ .

We use  $\deg_G(u)$  to denote the degree of a vertex u in G,  $d_G(u, v)$  the distance in G between u and v, and  $(u, \ldots, v)$  a path connecting u and v. The reader is referred to [3] for terminology undefined in the paper.

## 2 Results

Unlike the line graph L(G), the 3-arc graph X(G) is not necessarily connected even for connected G. Our first result, Theorem 2 below, tells us precisely when X(G) is connected. Define  $G^{\div}$  to be the graph obtained from G by replacing each vertex u of degree two by a pair u', u'' of nonadjacent vertices, each joined to exactly one neighbour of u. Note that u', u'' are degree-one vertices of  $G^{\div}$ . Thus,  $G^{\div}$  contains no degree-two vertex, and it has twice as many degree-one vertices as is the number of degree-two vertices in G. In particular, if  $\delta(G) \geq 3$ , then  $G^{\div} = G$ .

**Theorem 2** Let G be a connected graph with  $\delta(G) \ge 2$ . Then X(G) is connected if and only if  $G^{\div}$  is connected. In particular, if  $\delta(G) \ge 3$ , then X(G) is connected.

Next we consider the connectivity  $\kappa$ . X(G) can be disconnected when  $1 \le \kappa(G) \le 2$ . In the case  $\kappa(G) \ge 3$ , we can bound the connectivity of X(G) in terms of the connectivity of G.

**Theorem 3** Let G be a graph with connectivity  $\kappa(G) \geq 3$ . Then

$$\kappa(X(G)) \ge (\kappa(G) - 1)^2.$$

Moreover, this bound is best possible.

In fact, for any maximally connected k-regular graph G (that is,  $\kappa(G) = k$ ), where  $k \ge 3$ , X(G) is a  $(k-1)^2$ -regular graph and thus cannot be more than  $(k-1)^2$ -connected. Hence  $\kappa(X(G)) = (\kappa(G) - 1)^2$  and the bound in Theorem 3 is attained by G.

Denote by diam the diameter of a graph. We will prove the following results.

**Theorem 4** Let G be a connected graph with  $\delta(G) \geq 3$ . Then

 $\operatorname{diam}(G) \le \operatorname{diam}(X(G)) \le \operatorname{diam}(G) + 2$ 

with both bounds attainable. In addition, the lower bound holds as long as G has at least two vertices.

**Theorem 5** Let r and s be arbitrary integers such that  $4 \le r \le s - 4$  and  $s \ge 10$ . Then there exists a graph  $G_{r,s}$  such that diam $(G_{r,s}) = r$  and diam $(X(G_{r,s})) = s$ .

By Theorem 4 any graph  $G_{r,s}$  satisfying the conditions of Theorem 5 must satisfy  $\delta(G_{r,s}) = 2$ , because otherwise we would have  $r \leq s \leq r+2$  which violates  $r \leq s-4$ . Theorem 5 shows that diam(X(G)) can be arbitrarily large when diam $(G) \geq 4$  (and  $\delta(G) = 2$ ). This is not the case if diam $(G) \leq 3$  as indicated by the following result.

**Theorem 6** Let G be a connected graph such that X(G) is connected. Then the following hold:

- (a) if diam(G) = 1, then diam(X(G)) = 2;
- (b) if diam(G) = 2, then diam $(X(G)) \le 7$ ;
- (c) if diam(G) = 3, then diam $(X(G)) \le 14$ .

Let G be the graph obtained from a 6-cycle  $(u_0, u_1, u_2, u_3, u_4, u_5, u_0)$  by adding two chords  $\{u_0, u_2\}$  and  $\{u_2, u_4\}$ . Then diam(G) = 2 and diam(X(G)) = 6 (with the diameter achieved by  $d_{X(G)}(u_0u_2, u_4u_2)$ ). This suggests that the bound (b) in Theorem 6 may be improved slightly. As regards to (c), we believe that it is far from being optimal.

We will prove Theorems 2 and 3 in Section 4, and Theorems 4, 5 and 6 in Section 5, after a preliminary result is given in Section 3.

### 3 Paths in 3-arc graphs

The trace of an edge  $\{u_0v_0, u_1v_1\}$  of X(G) is defined to be the edge  $\{u_0, u_1\}$  of G. It is clear that, for two adjacent edges of X(G), say  $\{u_0v_0, u_1v_1\}$  and  $\{u_1v_1, u_2v_2\}$ , the traces  $\{u_0, u_1\}$ and  $\{u_1, u_2\}$  are either adjacent in G (if  $u_0 \neq u_2$ ) or identical (if  $u_0 = u_2$ ). In the former case we have  $\deg_G(u_1) \geq 3$  as  $u_0, u_2$  and  $v_1$  are distinct neighbours of  $u_1$ , while in the latter case we have  $\deg_G(u_1) \geq 2$  as  $u_0 \neq v_1$ . In general, if  $P = (u_0v_0, u_1v_1, u_1v_1, \ldots, u_kv_k)$  is a path or walk in X(G), then the traces of  $\{u_0v_0, u_1v_1\}, \{u_1v_1, u_2v_2\}, \ldots, \{u_{k-1}v_{k-1}, u_kv_k\}$  form a walk  $(u_0, u_1, \ldots, u_k)$  in G, which we call the trace of P.

The following lemma regarding the trace of a shortest path will be used in the next two sections. Denote by  $G^{\times}$  the subgraph of a graph G induced by vertices of degree at least three.

**Lemma 7** Let G be a connected graph with  $\delta(G) \geq 2$  and let  $P = (u_0v_0, u_1v_1, \dots, u_kv_k)$  be a shortest path in X(G).

- (a) If  $k \ge 2$ , then  $(u_1, u_2, \dots, u_{k-1})$  is either a path or a cycle in G.
- (b) If  $k \ge 4$ , then  $u_2, u_3, \ldots, u_{k-2}$  all have degrees at least three and  $(u_2, u_3, \ldots, u_{k-2})$  is a shortest path in  $G^{\times}$ .

**Proof** First we show that in the trace of P no edge can appear twice except possibly  $\{u_0, u_1\} = \{u_1, u_2\}$  or  $\{u_{k-2}, u_{k-1}\} = \{u_{k-1}, u_k\}$ . By way of contradiction suppose that  $\{u_i, u_{i+1}\} = \{u_j, u_{j+1}\}$  for some i < j with  $(i, j) \neq (0, 1), (k-2, k-1)$ . We show that there exists a path in X(G) between  $u_0v_0$  and  $u_kv_k$  which is shorter than P. In fact, if  $u_i = u_j$  and  $u_{i+1} = u_{j+1}$ , then  $u_i \neq v_{j+1}$  and  $v_i \neq u_{j+1}$ , and hence P can be shortened to  $(u_0v_0, \ldots, u_iv_i, u_{j+1}v_{j+1}, u_{j+2}v_{j+2}, \ldots, u_kv_k)$ . So we assume  $u_i = u_{j+1}$  and  $u_{i+1} = u_j$  in the following. If i + 1 < j, then P can be shortened to  $(u_0v_0, \ldots, u_iv_i, u_{i+1}v_{i+1}, u_{j+1}v_{j+1}, \ldots, u_kv_k)$ . Hence we may further assume i + 1 = j so that  $u_i = u_{i+2}$ . Since  $(i, j) \neq (0, 1), (k-2, k-1)$ , we have  $2 \leq i+1 = j \leq k-2$ . If  $u_{i-1} = u_{i+1}$ , then  $u_{i-1} = u_j$  and  $u_i = u_{j+1}$ , but this case was already excluded. The case  $u_j = u_{j+2}$  can be treated similarly. If  $u_{i-1} = u_{j+2}$ , then  $\{u_{i-1}, u_i\} = \{u_{j+1}, u_{j+2}\}$ , and since  $u_i = u_{j+1}$  and (i-1) + 1 < j+1, this case was already solved. Hence we may assume that  $u_{i-1}$ ,  $u_{i+1} (=u_j)$  and  $u_{j+2}$  are pairwise distinct. However, this implies that P can be shortened to  $(u_0v_0, \ldots, u_{i-1}v_{i-1}, u_iu_{i+1}, u_{j+2}v_{j+2}, \ldots, u_kv_k)$ .

Now we prove (a). Suppose  $u_i = u_j$  for some  $1 \le i < j \le k-1$  and suppose that  $\deg_G(u_i) \ge 3$ . Then  $u_i$  has a neighbour x other than  $u_{i-1}$  and  $u_{j+1}$ , and so P can be shortened to  $(u_0v_0, \ldots, u_{i-1}v_{i-1}, u_ix, u_{j+1}v_{j+1}, \ldots, u_kv_k)$ , a contradiction. Hence we may assume  $\deg_G(u_i) = 2$ . As  $1 \le i < k-1$ , the trace of P contains  $u_{i-1}$  and  $u_{i+1}$ . These two vertices must be distinct from  $v_i$ , so that  $u_{i-1} = u_{i+1}$ . Consequently, the edge  $\{u_{i-1}, u_i\} = \{u_i, u_{i+1}\}$  appears

twice on the trace and since i < k-1, by previous part of this proof we have i = 1. Analogously we can prove j = k-1, which finishes the proof of (a).

In fact, we proved more. We proved that all  $u_2, u_3, \ldots, u_{k-2}$  have degrees at least 3. Hence, it remains to prove that  $u_2, u_3, \ldots, u_{k-2}$  is a shortest path in  $G^{\times}$ . Let  $(z_2, z_3, \ldots, z_{t-2})$  be any path connecting  $z_2 = u_2$  and  $z_{t-2} = u_{k-2}$  in  $G^{\times}$ . Denote  $z_1 = u_1$  and  $z_{t-1} = u_{k-1}$ . Since the degrees of  $z_2, z_3, \ldots, z_{t-2}$  are at least three, for every *i* there is a neighbour  $w_i$  of  $z_i$  distinct from  $z_{i-1}$ and  $z_{i+1}, 2 \leq i \leq t-2$ . But then  $Q = (u_0v_0, u_1v_1, z_2w_2, z_3w_3, \ldots, z_{t-2}w_{t-2}, u_{k-1}v_{k-1}, u_kv_k)$  is a path in X(G). Hence we obtain (b) by taking for  $(z_2, z_3, \ldots, z_{t-2})$  the shortest path connecting  $z_2 = u_2$  and  $z_{t-2} = u_{k-2}$  in  $G^{\times}$ .

## 4 Proof of Theorems 2 and 3

In the proof of Theorem 2 we use Lemma 7.

**Proof of Theorem 2** Let G be a connected graph with  $\delta(G) \geq 2$ . Suppose first that  $G^{\div}$  is connected. We prove that there is a path between any two distinct vertices  $u_1v_1$  and  $u_2v_2$  of X(G).

Consider the case  $u_1 = u_2$  first. In this case, if  $\deg_G(u_1) \ge 3$ , then there is a neighbour  $x \ne v_1, v_2$  of  $u_1$ . Let y be a neighbour of x other than  $u_1$ . Then  $(u_1v_1, xy, u_2v_2)$  is a path of length two in X(G) connecting  $u_1v_1$  and  $u_2v_2$ , and we are done. So we may suppose  $\deg_G(u_1) = 2$ . Let  $u'_1$  and  $u''_1$  be the two vertices of  $G^{\div}$  obtained by splitting  $u_1$ . Since  $G^{\div}$  is connected, there is a path from  $u'_1$  to  $u''_1$  in  $G^{\div}$ . All internal vertices on this path must have degree at least three in G. Hence there exists a cycle C in G containing  $u_1$  such that all its vertices except  $u_1$  have degree at least three in G. Let  $W_0 = (u_1, v_2, \ldots, v_1, u_1)$  be the walk in G starting at  $u_1$ , then traversing all edges of C and terminating at  $u_1$ . That is, we prescribe the direction in which  $W_0$  traverses C.

Now suppose  $u_1 \neq u_2$ . Since  $G^{\div}$  is connected, there is a path  $W_0$  in G starting at  $u_1$  and terminating at  $u_2$ , such that all internal vertices of  $W_0$  have degree at least three. Moreover, if  $\deg_G(u_1) = 2$ , we may assume  $W_0 = (u_1, w_1, \ldots, u_2)$ , where  $w_1$  is the unique neighbour of  $u_1$  other than  $v_1$ ; if  $\deg_G(u_2) = 2$ , we may assume  $W_0 = (u_1, \ldots, u_2)$ , where  $w_2$  is the unique neighbour of  $u_2$  other than  $v_2$ .

In both possibilities above, the internal vertices of  $W_0$  have degree at least three. Let  $W_0 = (u_1, w_1, \ldots, w_2, u_2)$ . From the choice of  $W_0$ , the case  $w_1 = v_1$  occurs only when  $\deg_G(u_1) \ge 3$ , and in this case we extend  $W_0$  by adding the prefix  $(u_1, x_1, u_1)$ , where  $x_1 \ne v_1 (=w_1)$  is a neighbour of  $u_1$ . Analogously, the case  $w_2 = v_2$  occurs only when  $\deg_G(u_2) \ge 3$ , and in this case we extend  $W_0$  by adding the suffix  $(u_2, x_2, u_2)$ , where  $x_2 \ne v_2 (=w_2)$  is a neighbour of  $u_2$ . Let W be the walk obtained this way in these two cases, and define  $W = W_0$  otherwise. In the following we construct a path P in X(G) connecting  $u_1v_1$  and  $u_2v_2$  with trace W.

If W differs from  $W_0$  at the beginning, then P starts with  $(u_1v_1, x_1y_1, u_1z_1, ...)$ , where  $y_1$  is a neighbour of  $x_1$  different from  $u_1$ , and  $z_1$  is a neighbour of  $u_1$  different from  $x_1$  and  $v_1 (=w_1)$ . If W differs from  $W_0$  at the end, then P terminates with  $(\ldots, u_2z_2, x_2y_2, u_2v_2)$ , where  $y_2$  is a neighbour of  $x_2$  different from  $u_2$ , and  $z_2$  is a neighbour of  $u_2$  different from  $x_2$  and  $v_2 (=w_2)$ . Denote  $W_0 = (a_0, a_1, \ldots, a_k)$ , where  $a_0 = u_1$  and  $a_k = u_2$ . In all cases it suffices to construct the part  $P_0$  of P whose trace is  $W_0$ . Note that the end-vertices of  $P_0$  are already defined, namely,  $P_0 = (a_0b_0, \ldots, a_kb_k)$ , where  $a_0b_0 = u_1z_1$  if  $a_1 = v_1$  and  $a_0b_0 = u_1v_1$  otherwise, and  $a_kb_k = u_2z_2$ if  $a_{k-1} = v_2$  and  $a_kb_k = u_2v_2$  otherwise. Since  $\deg_G(a_i) \ge 3$ , 0 < i < k, there exists a neighbour  $b_i$  of  $a_i$  in G other than  $a_{i-1}$  and  $a_{i+1}$ . Let  $P_0 = (a_0b_0, a_1b_1, a_2b_2, \ldots, a_{k-1}b_{k-1}, a_kb_k)$ . Then  $P_0$ is a path in X(G) with trace  $W_0$ . Adding the prefix or suffix to  $P_0$  whenever applicable, we obtain the desired path P connecting  $u_1v_1$  and  $u_2v_2$ . Up to now we have proved that if  $G^{\div}$  is connected then so is X(G).

Now suppose that  $G^{\div}$  is a disconnected graph. Then, since G is connected, it contains a vertex u of degree two such that u' and u'' are in different connected components of  $G^{\div}$ . Denote by  $v_1$  and  $v_2$ , respectively, the two neighbours of u in G. Suppose that there is a path in X(G) connecting  $uv_1$  with  $uv_2$ , and denote by  $P = (uv_1, x_1y_1, x_2y_2, \ldots, x_{k-1}y_{k-1}, uv_2)$  a shortest one. Observe that  $x_1 = v_2$  and  $x_{k-1} = v_1$ . In the next we consider the trace of P. Since  $uv_1$  and  $uv_2$  are not adjacent in X(G),  $k \ge 2$ . By Lemma 7, all  $x_2, x_3, \ldots, x_{k-2}$  have degrees at least three. If one of  $x_1$  and  $x_{k-1}$  has degree two in G then G has adjacent vertices of degree two and consequently X(G) is disconnected. Hence, we may assume that  $x_1, x_2, \ldots, x_{k-1}$  is a path connecting  $v_2$  with  $v_1$  in  $G^{\times}$ , so that  $u'', x_1, x_2, \ldots, x_{k-1}, u'$  is a path in  $G^{\div}$ , a contradiction.  $\Box$ 

Possibly due to the relation explained in the introduction, the paths constructed in the proof of Theorem 3 are very similar to those constructed for 2-iterated line graphs [9] and 2-path graphs [10].

**Proof of Theorem 3** We will use the following version of Menger's theorem: A graph G is k-connected if and only if it has more than k vertices and for each pair of nonadjacent vertices there exist k internally-vertex-disjoint paths connecting them.

Denote  $k = \kappa(G)$ . Let  $x_1y_1$  and  $x_2y_2$  be distinct and nonadjacent vertices of X(G). We prove  $\kappa(X(G)) \ge (k-1)^2$  by constructing  $(k-1)^2$  internally-vertex-disjoint paths connecting  $x_1y_1$  and  $x_2y_2$  in X(G).

CASE 1: Consider the case  $x_1 = x_2$  first. Since  $\delta(G) \ge k$ ,  $x_1$  has k-2 neighbours which are distinct from  $y_1$  and  $y_2$ . Denote these neighbours by  $y_3, y_4, \ldots, y_k$ . Further, for  $3 \le i \le k$ ,  $y_i$  has k-1 neighbours, say,  $z_{i,1}, z_{i,2}, \ldots, z_{i,k-1}$ , which are distinct from  $x_1$ . Define  $P_{i,j} =$  $(x_1y_1, y_iz_{i,j}, x_1y_2), 3 \le i \le k, 1 \le j \le k-1$ . These are (k-2)(k-1) internally-vertex-disjoint paths in X(G) connecting  $x_1y_1$  and  $x_1y_2$ . Since  $k = \kappa(G)$ ,  $G - \{x_1, y_3, y_4, \dots, y_k\}$  is connected. Let  $P = (a_1, a_2, \dots, a_{t-1})$  be a path in  $G - \{x_1, y_3, y_4, \dots, y_k\}$  connecting  $a_1 = y_1$  and  $a_{t-1} = y_2$ . Since  $\delta(G) \geq k$ , we may choose k-2 neighbours  $u_3, u_4, \ldots, u_k$  of  $a_1$  other than  $x_1$  and  $a_2$ , and k-2neighbours  $v_3, v_4, \ldots, v_k$  of  $a_{t-1}$  other than  $x_1$  and  $a_{t-2}$ . Define  $P_i = (x_1y_1, y_2v_i, x_1y_i, y_1u_i, x_1y_2)$ ,  $3 \le i \le k$ . These are internally-vertex-disjoint paths, and none of them contains any internal vertex of any  $P_{i,j}$ . Now we have found  $(k-1)(k-2) + (k-2) = (k-1)^2 - 1$  internally-vertexdisjoint paths connecting  $x_1y_1$  and  $x_1y_2$ , so it remains to construct the last one. If  $\deg_G(x_1) > k$ then  $x_1$  had a neighbour  $y_0$  distinct from  $y_1, y_2, y_3, \ldots, y_k$  and we can find another (k-1) paths of type  $P_{i,i}$ . Hence, suppose that  $\deg_G(x_1) = k$ . Set  $a_0 = x_1 = x_2 = a_t$ , and for  $1 \le i \le t-1$ choose a neighbour  $b_i$  of  $a_i$  distinct from  $a_{i-1}$  and  $a_{i+1}$ . Since  $\deg_G(x_1) = k, a_i \notin \{y_3, y_4, \dots, y_k\}$ ,  $b_1 \neq a_0$  and  $b_{t-1} \neq a_t$ , we have  $b_i \neq x_1$ . Choose a neighbour  $c_i$  of  $b_i$  distinct from  $a_i, 1 \leq i \leq i$ t-1. In the case  $b_i = y_j$  for some  $3 \leq j \leq k$ , we simply set  $c_i = x_1$ . Consider the walk  $W = (a_0 a_{t-1}, a_1 a_2, b_1 c_1, a_1 a_0, a_2 a_3, b_2 c_2, a_2 a_1, \dots, a_{t-1} a_t, b_{t-1} c_{t-1}, a_{t-1} a_{t-2}, a_t a_1)$  (noting that  $a_0a_{t-1} = x_1y_2$  and  $a_ta_1 = x_1y_1$ ). This walk is internally-vertex-disjoint with  $P_{i,j}$ 's and  $P_l$ 's constructed above. It may happen that  $b_i c_i = b_j c_j$  for some  $i \neq j$ , and so W may not be a

path. However, by deleting redundant subwalks from W when necessary we can obtain a path connecting  $x_1y_1$  and  $x_1y_2$  as required.

CASE 2: Now we consider the case  $x_1 \neq x_2$ .

SUBCASE 2.1: Suppose first that  $x_1$  and  $x_2$  are not adjacent in G. Since G is k-connected, there are k internally-vertex-disjoint paths connecting  $x_1$  with  $x_2$  in G. Denote these paths by  $R_i = (a_{i,0}, a_{i,1}, \dots, a_{i,t_i}), \ 0 \le i \le k-1$ , where we set  $a_{i,0} = x_1$  and  $a_{i,t_i} = x_2$ . Since  $k \ge 3$ , we may assume that  $R_{k-1}$  does not pass through  $y_1$  and  $y_2$ . Since  $\delta(G) \ge k$ , for  $0 \le i \le k-1$ and  $1 \leq j \leq t_i - 1$  we may choose k - 2 neighbours  $b_{i,j,1}, b_{i,j,2}, \ldots, b_{i,j,k-2}$  of  $a_{i,j}$  different from  $a_{i,j-1}$  and  $a_{i,j+1}$ . Define  $P'_{i,j} = (a_{i,1}b_{i,1,j}, a_{i,2}b_{i,2,j}, \dots, a_{i,t_i-1}b_{i,t_i-1,j}), 0 \le i \le k-1, 1 \le j \le k-2$ which are k(k-2) vertex-disjoint paths in X(G). If  $y_1 \neq a_{i,1}$ , then we extend  $P'_{i,j}$   $(1 \leq j \leq k-2)$ at the beginning by adding  $x_1y_1$ . Similarly, if  $y_2 \neq a_{i,t_i-1}$ , then we extend  $P'_{i,j}$   $(1 \leq j \leq k-2)$ at the end by adding  $x_2y_2$ . There is at most one i with  $y_1 = a_{i,1}$  (which is less than k-1since  $R_{k-1}$  does not contain  $y_1$ , and for this i we extend  $P'_{i,j}$   $(1 \le j \le k-2)$  at the beginning by adding  $(x_1y_1, a_{i+j,1}a_{i+j,2}, x_1a_{n_{i,j},1})$  where the addition in subscript is modulo k-1,  $n_{i,j} \equiv i+j+1 \pmod{k-1}$  if  $1 \leq j < k-2$  and k > 3,  $n_{i,j} \equiv i+1 \pmod{k-1}$  if j = k-2 and k > 3, and  $n_{i,j} = k-1$  if k = 3. Observe that these prefixes are, with the exception of  $x_1y_1$ , vertex-disjoint. Similarly, there is at most one i < k-1 such that  $y_2 = a_{i,t_i-1}$ , and for this i we extend  $P'_{i,j}$   $(1 \le j \le k-2)$  at the end by adding  $(x_2 a_{n_{i,j},t_n-1}, a_{i+j,t_{i+j}-1}a_{i+j,t_{i+j}-2}, x_2 y_2)$ where the subscripts have the same meaning as above. Denote the extended form of  $P'_{i,j}$  by  $P_{i,j}$ . Then  $P_{i,j}$ 's are  $(k-1)^2 - 1$  internally-vertex-disjoint paths connecting  $x_1y_1$  and  $x_2y_2$ . It remains to construct the last path, which starts with  $(x_1y_1, a_{k-1,1}a_{k-1,2})$  and terminates with  $(a_{k-1,t_{k-1}-1}a_{k-1,t_{k-1}-2}, x_2y_2)$ . To abbreviate the notation set q = k-1. Choose a neighbour  $c_j \neq a_{q,j}$  of  $b_{q,j,1}$ ,  $1 \leq j \leq t_1 - 1$ . Assuming that the path  $R_{k-1}$  has no redundant parts, i.e., it is as short as possible, we get  $b_{q,j,1} \neq x_1, x_2$ . However, it may happen that  $b_{q,j,1} = a_{m,n}$  for some m and n. In this case we choose  $c_j = a_{m,n-1}$  if  $n \leq t_m/2$  and  $c_j = a_{m,n+1}$  otherwise. The walk W = $(x_1y_1, a_{q,1}a_{q,2}, b_{q,1,1}c_1, a_{q,1}x_1, a_{q,2}a_{q,3}, b_{q,2,1}c_2, a_{q,2}a_{q,1}, \dots, a_{q,t_q-1}x_2, b_{q,t_q-1,1}c_{t_q-1}, a_{q,t_q-1}a_{q,t_q-2}, \dots, a_{q,t_q-1}x_2, a_{q,t_q-1}x_2, a_{q,t_q-1}a_{q,t_q-2}, \dots, a_{q,t_q-1}x_2, a_{q,t_q-1}x_2, \dots, a_{q,t_q-1}x_2,$  $x_2y_2$ ) is internally-vertex-disjoint with all  $P_{i,j}$ 's. Therefore, we can obtain from W a path between  $x_1y_1$  and  $x_2y_2$  which is internally-vertex-disjoint with all  $P_{i,j}$ 's. Altogether we have constructed  $(k-1)^2$  internally-vertex-disjoint paths in X(G) between  $x_1y_1$  and  $x_2y_2$ .

SUBCASE 2.2: Now we deal with the case where  $x_1$  and  $x_2$  are adjacent in G. Since G is k-connected, there are k-1 internally-vertex-disjoint paths of length at least two connecting  $x_1$  and  $x_2$ . Denote these paths by  $R_i = (a_{i,0}, a_{i,1}, \ldots, a_{i,t_i}), 0 \le i \le k-2$ , where  $a_{i,0} = x_1$  and  $a_{i,t_i} = x_2$ . For  $0 \le i \le k-2$  and  $1 \le j \le t_i - 1$ , let  $b_{i,j,1}, b_{i,j,2}, \ldots, b_{i,j,k-2}$  be k-2 neighbours of  $a_{i,j}$  distinct from  $a_{i,j-1}$  and  $a_{i,j+1}$ . Since  $x_1, x_2$  are adjacent in G and  $x_1y_1, x_2y_2$  are not adjacent in X(G), we have  $\{x_1, y_1\} \cap \{x_2, y_2\} \ne \emptyset$ , and hence by symmetry we need to consider the following two possibilities only.

The first possibility is that  $y_1 = x_2$  and  $y_2 = x_1$ . In this case, for  $0 \le i \le k-2$ and  $1 \le j \le k-2$ , define  $P_{i,j} = (x_1y_1, a_{i,1}b_{i,1,j}, a_{i,2}b_{i,2,j}, \ldots, a_{i,t_i-1}b_{i,t_i-1,j}, x_2y_2)$  and  $Q_i = (x_1y_1, a_{i,1}a_{i,2}, x_1a_{i+1,1}, x_2a_{i+1,t_{i+1}-1}, a_{i,t_i-2}, x_2y_2)$ , where subscripts are taken modulo k-1. Obviously, these are  $(k-1)(k-2)+(k-1)=(k-1)^2$  internally-vertex-disjoint paths in X(G) connecting  $x_1y_1$  and  $x_2y_2$ .

In the second possibility, we may assume  $y_1 = x_2$  and  $y_2 \neq x_1$ . In the case when  $y_2$  appears on some path  $R_i$ , we may assume without loss of generality that  $y_2 = a_{0,t_0-1}$ . Consider the paths  $P'_{i,j} = (x_1y_1, a_{i,1}b_{i,1,j}, a_{i,2}b_{i,2,j}, \dots, a_{i,t_i-1}b_{i,t_i-1,j}), 0 \leq i \leq k-2, 1 \leq j \leq k-2$ . We extend  $P'_{i,j}$   $(1 \le i \le k-2, 1 \le j \le k-2)$  at the end by adding  $x_2y_2$ . Then we extend  $P'_{0,j}$  $(1 \le j \le k-2)$  at the end by adding  $(x_2a_{j,t_j-1}, a_{j+1,t_{j+1}-1}a_{j+1,t_{j+1}-2}, x_2y_2)$  if j < k-2 and  $(x_2x_1, a_{1,t_1-1}a_{1,t_1-2}, x_2y_2)$  if j = k-2. (Note that only the latter case applies when k = 3.) Denote by  $P_{i,j}$  the extension of  $P'_{i,j}$  obtained this way. Define  $Q_i = (x_1y_1, a_{i,1}a_{i,2}, x_1a_{i+1,1}, x_2y_2)$ ,  $0 \le i \le k-2$ , where subscripts are taken modulo k-1. Then  $P_{i,j}$ 's and  $Q_i$ 's are  $(k-1)(k-2) + (k-1) = (k-1)^2$  internally-vertex-disjoint paths in X(G) connecting  $x_1y_1$  and  $x_2y_2$ .

That the bound  $\kappa(X(G)) \ge (k-1)^2$  is best possible was explained right after the statement of Theorem 3.

## 5 Proof of Theorems 4, 5 and 6

Given vertex-disjoint graphs  $G_1, G_2, \ldots, G_k$ , define  $G_1 \vee G_2 \vee \cdots \vee G_k$  to be the graph obtained from the union  $G_1 \cup G_2 \cup \cdots \cup G_k$  by adding all possible edges joining a vertex of  $G_i$  with a vertex of  $G_{i+1}, 1 \leq i \leq k-1$ . Let  $K_n$  denote the complete graph on n vertices.

**Proof of Theorem 4** Let us prove the upper bound first. Suppose  $\delta(G) \geq 3$  and let  $x_1y_1$ and  $x_2y_2$  be vertices of X(G) with  $d_{X(G)}(x_1y_1, x_2y_2) = \operatorname{diam}(X(G))$ . Let  $z_1$  be a neighbour of  $x_1$  different from  $y_1$ , and  $z_2$  a neighbour of  $x_2$  different from  $y_2$ . Let  $(a_1, a_2, \ldots, a_{k-1})$  be a shortest path in G between  $a_1 = z_1$  and  $a_{k-1} = z_2$ . Set  $a_0 = x_1$  and  $a_k = x_2$ . Since  $\delta(G) \geq 3$ , for each  $1 \leq i \leq k-1$  there exists a vertex  $b_i$  adjacent to  $a_i$  and different from  $a_{i-1}$  and  $a_{i+1}$ . Since  $a_1 \neq y_1$  and  $a_{k-1} \neq y_2$ ,  $(x_1y_1, a_1b_1, a_2b_2, \ldots, a_{k-1}b_{k-1}, x_2y_2)$  is a path in X(G). Therefore, diam $(X(G)) = d_{X(G)}(x_1y_1, x_2y_2) \leq d_G(a_1, a_{k-1}) + 2 \leq \operatorname{diam}(G) + 2$ .

To prove the lower bound we require only that G is nontrivial, since otherwise X(G) is an empty graph. Let  $x_1$  and  $x_2$  be vertices of G such that  $d_G(x_1, x_2) = \operatorname{diam}(G)$ . Let  $y_1$  be a neighbour of  $x_1$  and  $y_2$  a neighbour of  $x_2$ . Assume that X(G) is connected and denote by P a shortest path in X(G) between  $x_1y_1$  and  $x_2y_2$ . Then the trace of P is a walk starting at  $x_1$  and terminating at  $x_2$ , and the length of this walk cannot be shorter than the distance between  $x_1$  and  $x_2$  in G. Hence,  $\operatorname{diam}(G) = d_G(x_1, x_2) \leq d_{X(G)}(x_1y_1, x_2y_2) \leq \operatorname{diam}(X(G))$ .

Let  $G_2 = K_3 \vee K_1 \vee K_3$ , and for  $k \ge 3$  let  $G_k = K_3 \vee K_1 \vee K_2 \vee \cdots \vee K_2 \vee K_1 \vee K_3$ , where there are k - 3 copies of  $K_2$  in  $G_k$ . Then diam $(G_k) = k$  and diam $(X(G_k)) = k + 2$ , and hence the upper bound is attained by  $G_k$ . (The diameter of  $X(G_k)$  is achieved by  $d_{X(G_k)}(x_1y_1, x_2y_2)$ , where  $x_1$  and  $x_2$  are from different copies of  $K_3$  and  $y_1$  and  $y_2$  are from copies of  $K_1$ .) Let  $H_k = K_3 \vee K_2 \vee \cdots \vee K_2 \vee K_3$ , where there are  $k - 1 \ge 1$  copies of  $K_2$ . Then diam $(H_k) =$ diam $(X(H_k)) = k$ , and so the lower bound is attainable as well.

**Proof of Theorem 5** Let  $P_s = (a_0, a_1, \ldots, a_{s-4})$  be a path of length s - 4. We add several vertices and edges to  $P_s$ :

- (1) First we add two vertices  $b_0$  and  $b_{s-4}$ , join  $b_0$  to  $a_0$  and  $a_2$ , and join  $b_{s-4}$  to  $a_{s-6}$  and  $a_{s-4}$ ;
- (2) then we add vertices  $c_1, c_2, \ldots, c_{s-5}$  and join  $c_i$  to  $a_{i-1}$  and  $a_{i+1}, 1 \leq j \leq s-5$ .

Denote by  $H_s$  the resulting graph.

(3) We then add to  $H_s$  some vertices  $d_{i,j}$ ,  $0 \le i < j \le s-4$ , and join  $d_{i,j}$  to  $a_i$  and  $a_j$ , in the following manner: We first add  $d_{i,j}$  (and the corresponding edges) with j - i = 3. Then

we add  $d_{i,j}$  (and the corresponding edges) with j - i = 4, and so on until we obtain a graph of diameter r.

Denote the resultant graph by  $G_{r,s}$ . First of all, we have to show that adding vertices  $d_{i,j}$  successively in step (3) can indeed create a graph of diameter r. In fact, we have diam $(H_s) = d_{H_s}(a_0, a_{s-4}) = s - 4$ , and at each step of adding a single vertex  $d_{i,j}$  together with the corresponding edges  $\{d_{i,j}, a_i\}$  and  $\{d_{i,j}, a_j\}$ , the diameter can decrease by at most one, since we connect vertices at distance 3 by a path of length 2. Moreover, if we add all possible vertices  $d_{i,j}$  with  $j - i \ge 3$  together with the corresponding edges, then we get a graph of diameter 4. (As  $s \ge 10$ , we have  $d_{G_{r,s}}(b_0, b_{s-4}) \ge 4$ .) Since  $4 \le r \le s - 4$ , there exists a time at which we obtain a graph  $G_{r,s}$  of diameter r.

Now we prove diam $(X(G_{r,s})) = s$ . Observe that all vertices of  $P_s$  have degree at least three in  $G_{r,s}$ , while all other vertices have degree two in  $G_{r,s}$ . From this one can see that  $G_{r,s}^{\div}$  is connected. Hence  $X(G_{r,s})$  is connected by Theorem 2.

Let P be a shortest path connecting two vertices of  $X(G_{r,s})$ , and let  $W = (u_0, u_1, \ldots, u_t)$ be the trace of P. Then by Lemma 7,  $u_2, u_3, \ldots, u_{t-2}$  all have degree at least three in  $G_{r,s}$ and  $(u_2, u_3, \ldots, u_{t-2})$  is a shortest path in  $G_{r,s}^{\times}$ . In view of the observation in the previous paragraph this implies that  $(u_2, u_3, \ldots, u_{t-2})$  is a subpath of  $P_s$ , and hence P has length at most 2 + (s-4) + 2 = s. Since P is an arbitrary shortest path in  $X(G_{r,s})$ , it follows that diam $(X(G_{r,s})) \leq s$ .

To prove the reverse inequality, consider the distance between  $a_0a_1$  and  $a_{s-4}a_{s-5}$  in  $X(G_{r,s})$ . Since in  $X(G_{r,s})$  the vertex  $a_0a_1$  is adjacent only to vertices xy such that  $\deg_{G_{r,s}}(x) = 2$ , the trace of any path in  $X(G_{r,s})$  joining  $a_0a_1$  with  $a_{s-4}a_{s-5}$  must start with  $(a_0, x, a_0, ...)$ . Analogously, since  $a_{s-4}a_{s-5}$  is adjacent only to vertices zw such that  $\deg_{G_{r,s}}(z) = 2$ , the trace of such a path must terminate with  $(\ldots, a_{s-4}, z, a_{s-4})$ . Thus, the trace of any path joining  $a_0a_1$  with  $a_{s-4}a_{s-5}$ is of the form  $(a_0, x, a_0, \ldots, a_{s-4}, z, a_{s-4})$ . By Lemma 7 all vertices of its subpath  $(a_0, \ldots, a_{s-4})$ must have degree at least three, so they form a walk in  $P_s$ . Consequently the trace of any shortest path in  $X(G_{r,s})$  between  $a_0a_1$  and  $a_{s-4}a_{s-5}$  must have length at least 2+(s-4)+2=s, so that  $d_{X(G_{r,s})}(a_0a_1, a_{s-4}a_{s-5}) \ge s$ . Hence, diam $(X(G_{r,s})) \ge s$ .

**Proof of Theorem 6** If diam(G) = 1, then G is a complete graph. Moreover, it has at least four vertices as X(G) is connected. It can be easily verified that diam(X(G)) = 2.

Now suppose diam(G) = 2 and diam $(X(G)) \ge 8$ . Then there exist  $u_0v_0$  and  $u_8v_8$  whose distance in X(G) is eight. Let  $P = (u_0v_0, u_1v_1, \ldots, u_8v_8)$  be a shortest path joining  $u_0v_0$  and  $u_8v_8$  in X(G). By Lemma 7,  $(u_2, u_3, \ldots, u_6)$  is a shortest path in  $G^{\times}$ . As  $u_2$  and  $u_5$  are not adjacent in  $G^{\times}$ , they are not adjacent in G. Since diam(G) = 2, we have  $d_G(u_2, u_5) = 2$  and so there exists a vertex  $x_1$  of degree two in G which is adjacent to both  $u_2$  and  $u_5$ . Similarly, there exists a vertex  $x_2$  of degree two which is adjacent to both  $u_3$  and  $u_6$ . Since  $x_1$  and  $x_2$  do not have any common neighbour,  $d_G(x_1, x_2) \ge 3$ , which contradicts our assumption diam(G) = 2.

Finally, suppose diam(G) = 3 and diam $(X(G)) \ge 15$ . Similarly to the above, there exists a shortest path P in X(G) with length 15 and trace  $(u_0, u_1, \ldots, u_{15})$ , say, such that  $(u_2, u_3, \ldots, u_{13})$  is a shortest path in  $G^{\times}$ . Since  $d_G(u_2, u_{13}) \le 3$ , there exists a vertex  $x_1$  of degree two which allows a "shortcut" between  $u_2$  and  $u_{13}$  in G. Then  $x_1$  is joined by an edge to  $u_2$  or  $u_{13}$ . Without loss of generality assume that  $x_1$  is adjacent to  $u_2$ . Then the other edge incident to  $x_1$  connects  $x_1$  with  $u_{13}$  or with a neighbour of  $u_{13}$ . Similarly, since  $d_G(u_5, u_9) \le 3$ , there exists a vertex

 $x_2$  of degree two which is adjacent to  $u_5$  or a neighbour of  $u_5$  and also to  $u_9$  or a neighbour of  $u_9$ . In any case, no neighbour of  $x_1$  is adjacent to a neighbour of  $x_2$ . Hence  $d_G(x_1, x_2) \ge 4$ , a contradiction.

Acknowledgements Martin Knor acknowledges partial support by Slovak research grants VEGA 1/0489/08, APVV-0040-06 and APVV-0104-07. Samming Zhou was supported by an ARC Discovery Project Grant (DP0558677) of the Australian Research Council.

## References

- C. Balbuena, P. García-Vázquez, A sufficient condition for P<sub>k</sub>-path graphs being r-connected, Discrete Appl. Math. 155 (2007), 1745–1751.
- [2] A. Belan, P. Jurica, Diameter in path graphs, Acta Math. Univ. Commenian. LXVIII (1999), 111–126.
- [3] J. A. Bondy and U. S. R. Murty, Graph Theory with Applications, Elsevier, North-Holland, 1976.
- [4] H.J. Broersma, C. Hoede, Path graphs, J. Graph Theory 13 (1989), 427-444.
- [5] A. Gardiner, C. E. Praeger and S. Zhou, Cross-ratio graphs, J. London Math. Soc. (2) 64 (2001), 257–272.
- [6] R. L. Hemminger and L. W. Beineke, Line graphs and line digraphs, in: L. W. Beineke and R. L. Wilson, eds., Selected Topics in Graph Theory, Academic Press, London, 1978.
- [7] M. A. Iranmanesh, C. E. Praeger and S. Zhou, Finite symmetric graphs with two-arc transitive quotients, J. Combin. Theory (Ser. B) 94 (2005), 79–99.
- [8] M. Knor and L'. Niepel, Path, trail and walk graphs, Acta. Math. Univ. Commenian. LXVIII (1999), 253–256.
- [9] M. Knor and L'. Niepel, Connectivity of iterated line graphs, Discrete Appl. Math. 125 (2003), 255-266.
- [10] M. Knor, L'. Niepel and M. Malah, Connectivity of path graphs, Australasian J. Comb. 25 (2002), 175–184.
- [11] C. H. Li, C. E. Praeger and S. Zhou, A class of finite symmetric graphs with 2-arc transitive quotients, Math. Proc. Cambridge Phil. Soc. 129 (2000), 19–34.
- [12] Z. Lu and S. Zhou, Finite symmetric graphs with 2-arc transitive quotients (II), J. Graph Theory, 56 (2007), 167–193.
- [13] L'. Niepel, M. Knor and L'. Šoltés, Distances in iterated line graphs, Ars Combin. 43 (1996), 193– 202.
- [14] E. Prisner, Line graphs and generalizations a survey, in: Surveys in Graph Theory, G. Chartrand and M. Jacobson, eds., Congr. Numer. 116 (1996), 193–229.
- [15] S. Zhou, Constructing a class of symmetric graphs, European J. Combin. 23 (2002), 741–760.
- [16] S. Zhou, Imprimitive symmetric graphs, 3-arc graphs and 1-designs, Discrete Math. 244 (2002), 521–537.
- [17] S. Zhou, Almost covers of 2-arc transitive graphs, Combinatorica 24 (2004), 731-745. [Erratum: 27 (2007), 745–746.]