

LINEAR TRANSFORMS, BASES and QUADRATIC OPTIMALITY CRITERIA for GAMES

Ulrich FAIGLE* and **Michel GRABISCH****

*Mathematisches Institut, Universität zu Köln, Germany

**Université de Paris I, Paris School of Economics, France

Introduction

- ▶ A well-known basis for games is the set of unanimity games. Coordinates correspond to the Möbius transform.

Introduction

- ▶ A well-known basis for games is the set of unanimity games. Coordinates correspond to the Möbius transform.
- ▶ Many other transforms exist (interaction, Walsh or Fourier, etc.), however the obvious duality **basis** ↔ **linear transform** has been overlooked.

Introduction

- ▶ A well-known basis for games is the set of unanimity games. Coordinates correspond to the Möbius transform.
- ▶ Many other transforms exist (interaction, Walsh or Fourier, etc.), however the obvious duality **basis**↔**linear transform** has been overlooked.
- ▶ As a consequence, the **inverse problem** for games (find all games having the same Shapley value) has been solved in a tedious way.

Introduction

- ▶ A well-known basis for games is the set of unanimity games. Coordinates correspond to the Möbius transform.
- ▶ Many other transforms exist (interaction, Walsh or Fourier, etc.), however the obvious duality **basis** ↔ **linear transform** has been overlooked.
- ▶ As a consequence, the **inverse problem** for games (find all games having the same Shapley value) has been solved in a tedious way.
- ▶ The Shapley value is an example of a **least square value** as it optimizes some least square criterion on games.

Introduction

- ▶ A well-known basis for games is the set of unanimity games. Coordinates correspond to the Möbius transform.
- ▶ Many other transforms exist (interaction, Walsh or Fourier, etc.), however the obvious duality **basis**↔**linear transform** has been overlooked.
- ▶ As a consequence, the **inverse problem** for games (find all games having the same Shapley value) has been solved in a tedious way.
- ▶ The Shapley value is an example of a **least square value** as it optimizes some least square criterion on games.
- ▶ **Aim of the paper:** to give a systematic analysis of the above aspects.

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$
- ▶ game $v : 2^N \rightarrow \mathbb{R}$ (here $v(\emptyset) = 0$ is not imposed).

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$
- ▶ game $v : 2^N \rightarrow \mathbb{R}$ (here $v(\emptyset) = 0$ is not imposed).
- ▶ The set of games on N , $\mathcal{G}(N)$, forms a vector space of dimension 2^n .

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$
- ▶ game $v : 2^N \rightarrow \mathbb{R}$ (here $v(\emptyset) = 0$ is not imposed).
- ▶ The set of games on N , $\mathcal{G}(N)$, forms a vector space of dimension 2^n .
- ▶ *Unanimity games* ζ_S , $S \subseteq N$:

$$\zeta_S = \begin{cases} 1, & \text{if } S \supseteq T \\ 0, & \text{otherwise.} \end{cases}$$

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$
- ▶ game $v : 2^N \rightarrow \mathbb{R}$ (here $v(\emptyset) = 0$ is not imposed).
- ▶ The set of games on N , $\mathcal{G}(N)$, forms a vector space of dimension 2^n .
- ▶ *Unanimity games* ζ_S , $S \subseteq N$:

$$\zeta_S = \begin{cases} 1, & \text{if } S \supseteq T \\ 0, & \text{otherwise.} \end{cases}$$

- ▶ *Identity games* δ_S , $S \subseteq N$:

$$\delta_S = \begin{cases} 1, & \text{if } S = T \\ 0, & \text{otherwise.} \end{cases}$$

Preliminary notions

- ▶ N set of n players, $\mathcal{N} = 2^N$
- ▶ game $v : 2^N \rightarrow \mathbb{R}$ (here $v(\emptyset) = 0$ is not imposed).
- ▶ The set of games on N , $\mathcal{G}(N)$, forms a vector space of dimension 2^n .
- ▶ *Unanimity games* ζ_S , $S \subseteq N$:

$$\zeta_S = \begin{cases} 1, & \text{if } S \supseteq T \\ 0, & \text{otherwise.} \end{cases}$$

- ▶ *Identity games* δ_S , $S \subseteq N$:

$$\delta_S = \begin{cases} 1, & \text{if } S = T \\ 0, & \text{otherwise.} \end{cases}$$

- ▶ scalar product $\langle v, w \rangle = \sum_{S \subseteq N} v(S)w(S)$

Bases and linear transforms

- ▶ A *transform* is a linear invertible mapping $\Psi : \mathcal{G}(N) \rightarrow \mathcal{G}(N)$;
 $v \mapsto \Psi v$

Bases and linear transforms

- ▶ A *transform* is a linear invertible mapping $\Psi : \mathcal{G}(N) \rightarrow \mathcal{G}(N)$;
 $v \mapsto \Psi v$
- ▶ To a game v , we make correspond a row vector $v \in \mathbb{R}^{\mathcal{N}}$

Bases and linear transforms

- ▶ A *transform* is a linear invertible mapping $\Psi : \mathcal{G}(N) \rightarrow \mathcal{G}(N)$;
 $v \mapsto \Psi v$
- ▶ To a game v , we make correspond a row vector $v \in \mathbb{R}^{\mathcal{N}}$
- ▶ To a basis $(f_S)_{S \in \mathcal{N}}$, we make correspond the matrix $F = [f_S]$ of row vectors f_S . Hence $v = \sum_{S \in \mathcal{N}} w_S f_S = wF$ is the expression of v in this basis.

Bases and linear transforms

- ▶ A *transform* is a linear invertible mapping $\Psi : \mathcal{G}(N) \rightarrow \mathcal{G}(N)$;
 $v \mapsto \Psi^v$
- ▶ To a game v , we make correspond a row vector $v \in \mathbb{R}^N$
- ▶ To a basis $(f_S)_{S \in \mathcal{N}}$, we make correspond the matrix $F = [f_S]$ of row vectors f_S . Hence $v = \sum_{S \in \mathcal{N}} w_S f_S = wF$ is the expression of v in this basis.

Lemma (Equivalence between bases and transforms)

For every basis F , there is a (unique) transform Ψ such that for any $v \in \mathbb{R}^N$,

$$v = \sum_{S \in \mathcal{N}} \Psi^v(S) f_S, \quad (1)$$

whose inverse Ψ^{-1} is given by $v \mapsto (\Psi^{-1})^v = \sum_{S \in \mathcal{N}} v(S) f_S = vF$. Conversely, to any transform Ψ corresponds a unique basis F such that (1) holds, given by $f_S = (\Psi^{-1})^{\delta_S}$.

Examples

The Möbius transform: associated with the basis of unanimity games

$$v(S) = \sum_{T \in \mathcal{N}} m^v(T) \zeta_T(S) = \sum_{T \subseteq S} m^v(T), \quad (T \subseteq N),$$

with

$$m^v(S) = \sum_{T \subseteq S} (-1)^{|S \setminus T|} v(T).$$

Examples

The Möbius transform: associated with the basis of unanimity games

$$v(S) = \sum_{T \in \mathcal{N}} m^v(T) \zeta_T(S) = \sum_{T \subseteq S} m^v(T), \quad (T \subseteq N),$$

with

$$m^v(S) = \sum_{T \subseteq S} (-1)^{|S \setminus T|} v(T).$$

The co-Möbius (or commonality) transform:

$$\check{m}^v(S) = \sum_{T \supseteq N \setminus S} (-1)^{n-|T|} v(T) = \sum_{T \subseteq S} (-1)^{|T|} v(N \setminus T) \quad (S \in \mathcal{N})$$

and $v(S) = \sum_{T \subseteq N \setminus S} (-1)^{|T|} \check{m}^v(T).$

Examples

The Möbius transform: associated with the basis of unanimity games

$$v(S) = \sum_{T \in \mathcal{N}} m^v(T) \zeta_T(S) = \sum_{T \subseteq S} m^v(T), \quad (T \subseteq N),$$

with

$$m^v(S) = \sum_{T \subseteq S} (-1)^{|S \setminus T|} v(T).$$

The co-Möbius (or commonality) transform:

$$\check{m}^v(S) = \sum_{T \supseteq N \setminus S} (-1)^{n-|T|} v(T) = \sum_{T \subseteq S} (-1)^{|T|} v(N \setminus T) \quad (S \in \mathcal{N})$$

and $v(S) = \sum_{T \subseteq N \setminus S} (-1)^{|T|} \check{m}^v(T)$. By the Lemma, the associated basis is

$$f_T(S) = \sum_{B \subseteq N \setminus S} (-1)^{|B|} \delta_T(B) = \begin{cases} (-1)^{|T|} & \text{if } S \cap T = \emptyset \\ 0 & \text{otherwise.} \end{cases}$$

The (Shapley) interaction transform:

$$I^v(S) = \sum_{T \subseteq N \setminus S} \frac{(n-t-s)!t!}{(n-s+1)!} \sum_{L \subseteq S} (-1)^{|S \setminus L|} v(T \cup L)$$

and the inverse relation

$$v(S) = \sum_{K \subseteq N} \beta_{|S \cap K|}^{|K|} I^v(K),$$

where

$$\beta_k^l = \sum_{j=0}^k \binom{k}{j} B_{l-j} \quad (k \leq l),$$

and B_0, B_1, \dots are the Bernoulli numbers.

The (Shapley) interaction transform:

$$I^v(S) = \sum_{T \subseteq N \setminus S} \frac{(n-t-s)!t!}{(n-s+1)!} \sum_{L \subseteq S} (-1)^{|S \setminus L|} v(T \cup L)$$

and the inverse relation

$$v(S) = \sum_{K \subseteq N} \beta_{|S \cap K|}^{|K|} I^v(K),$$

where

$$\beta_k^l = \sum_{j=0}^k \binom{k}{j} B_{l-j} \quad (k \leq l),$$

and B_0, B_1, \dots are the Bernoulli numbers. The associated basis $\{b_T^l\}_{T \in \mathcal{N}}$ is

$$b_T^l(S) = \beta_{|T \cap S|}^{|T|} \quad (S \in \mathcal{N})$$

The Banzhaf interaction transform:

$$I_B^v(S) = \left(\frac{1}{2}\right)^{n-s} \sum_{K \subseteq N} (-1)^{|S \setminus K|} v(K)$$

with inverse relation

$$(I_B^{-1})^v(S) = \sum_{K \subseteq N} \left(\frac{1}{2}\right)^k (-1)^{|K \setminus S|} v(K).$$

The Banzhaf interaction transform:

$$I_B^v(S) = \left(\frac{1}{2}\right)^{n-s} \sum_{K \subseteq N} (-1)^{|S \setminus K|} v(K)$$

with inverse relation

$$(I_B^{-1})^v(S) = \sum_{K \subseteq N} \left(\frac{1}{2}\right)^k (-1)^{|K \setminus S|} v(K).$$

The associated basis $\{b_T^{I_B}\}_{T \in \mathcal{N}}$ is

$$b_T^{I_B}(S) = \sum_{K \subseteq N} \left(\frac{1}{2}\right)^k (-1)^{|K \setminus S|} \delta_T(K) = \left(\frac{1}{2}\right)^{|T|} (-1)^{|T \setminus S|}.$$

The Hadamard transform:

$$H^v(S) = \frac{1}{2^{n/2}} \sum_{K \subseteq N} (-1)^{|S \cap K|} v(K)$$

(self-inverse relation).

The Hadamard transform:

$$H^v(S) = \frac{1}{2^{n/2}} \sum_{K \subseteq N} (-1)^{|S \cap K|} v(K)$$

(self-inverse relation). The corresponding basis $\{b_T^H\}_{T \in \mathcal{N}}$ is

$$b_T^H(S) = \frac{1}{2^{n/2}} \sum_{K \subseteq N} (-1)^{|S \cap K|} \delta_T(K) = \frac{1}{2^{n/2}} (-1)^{|S \cap T|}.$$

Examples

The Walsh basis $\{w_T\}_{T \in \mathcal{N}}$:

$$w_T(S) = (-1)^{|T \setminus S|} \quad (S \in \mathcal{N}).$$

It is an orthogonal basis.

The Walsh basis $\{w_T\}_{T \in \mathcal{N}}$:

$$w_T(S) = (-1)^{|T \setminus S|} \quad (S \in \mathcal{N}).$$

It is an orthogonal basis. The corresponding Walsh transform W satisfies

$$v(S) = \sum_{T \subseteq N} W^v(T) (-1)^{|T \setminus S|} \quad (S \in \mathcal{N}),$$

which yields

$$W^v(S) = \left(\frac{1}{2}\right)^{|S|} I_B^v(S) \quad (S \in \mathcal{N})$$

Examples

The Walsh basis $\{w_T\}_{T \in \mathcal{N}}$:

$$w_T(S) = (-1)^{|T \setminus S|} \quad (S \in \mathcal{N}).$$

It is an orthogonal basis. The corresponding Walsh transform W satisfies

$$v(S) = \sum_{T \subseteq N} W^v(T) (-1)^{|T \setminus S|} \quad (S \in \mathcal{N}),$$

which yields

$$W^v(S) = \left(\frac{1}{2}\right)^{|S|} I_B^v(S) \quad (S \in \mathcal{N})$$

Relation between the Hadamard basis and the Walsh basis:

$$b_T^H(S) = b_S^H(T) = \frac{1}{2^{n/2}} (-1)^{|S \cap T|} = \frac{1}{2^{n/2}} (-1)^{|S \setminus (N \setminus T)|} = \frac{1}{2^{n/2}} w_S(N \setminus T)$$

The inverse problem

- ▶ A *linear value* is a mapping $\Phi : \mathbb{R}^{\mathcal{N}} \rightarrow \mathbb{R}^{\mathcal{N}}$ assigning to any game a n -dim vector. Examples: the Shapley value Φ^{Sh} , the Banzhaf value Φ^{B} .

The inverse problem

- ▶ A *linear value* is a mapping $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ assigning to any game a n -dim vector. Examples: the Shapley value Φ^{Sh} , the Banzhaf value Φ^{B} .
- ▶ **Fact:** the Shapley (resp., Banzhaf) interaction transform extends the Shapley (resp., Banzhaf) value in the sense that

$$\Phi_i^{\text{Sh}}(v) = I^v(\{i\}), \quad \Phi_i^{\text{B}}(v) = I_B^v(\{i\}), \quad (i \in N)$$

The inverse problem

- ▶ A *linear value* is a mapping $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ assigning to any game a n -dim vector. Examples: the Shapley value Φ^{Sh} , the Banzhaf value Φ^{B} .
- ▶ **Fact:** the Shapley (resp., Banzhaf) interaction transform extends the Shapley (resp., Banzhaf) value in the sense that

$$\Phi_i^{\text{Sh}}(v) = I^v(\{i\}), \quad \Phi_i^{\text{B}}(v) = I_B^v(\{i\}), \quad (i \in N)$$

- ▶ *The inverse problem: Given a linear value Φ and a game v , find all games v' such that $\Phi(v) = \Phi(v')$.*

The inverse problem

- ▶ A *linear value* is a mapping $\Phi : \mathbb{R}^N \rightarrow \mathbb{R}^N$ assigning to any game a n -dim vector. Examples: the Shapley value Φ^{Sh} , the Banzhaf value Φ^{B} .
- ▶ **Fact:** the Shapley (resp., Banzhaf) interaction transform extends the Shapley (resp., Banzhaf) value in the sense that

$$\Phi_i^{\text{Sh}}(v) = I^v(\{i\}), \quad \Phi_i^{\text{B}}(v) = I_B^v(\{i\}), \quad (i \in N)$$

- ▶ *The inverse problem: Given a linear value Φ and a game v , find all games v' such that $\Phi(v) = \Phi(v')$.*
- ▶ Observe that v' is a solution iff $\Phi(v - v') = 0$, i.e., $v - v' \in \ker(\Phi)$. So it suffices to determine the kernel of the linear map Φ .

The inverse problem: Solution 1

Suppose you know a transform Ψ extending the value. Then the kernel is just the space spanned by the vectors f_S of the corresponding basis with $|S| > 1$.

$$v = \sum_{S \in \mathcal{N}} I^v(S) b'_S = \sum_{i \in \mathcal{N}} \Phi_i^{\text{Sh}}(v) b'_{\{i\}} + \sum_{|S| \neq 1} I^v(S) b'_S,$$

which implies

$$v \in \ker(\Phi^{\text{Sh}}) \iff v = \sum_{|S| \neq 1} I^v(S) b'_S$$

i.e.,

$$\ker(\Phi^{\text{Sh}}) = \left\{ \sum_{|S| \neq 1} \lambda_S b'_S \mid \lambda_S \in \mathbb{R} \right\}$$

The inverse problem: Solution 1

Suppose you know a transform Ψ extending the value. Then the kernel is just the space spanned by the vectors f_S of the corresponding basis with $|S| > 1$.

Illustration with the Shapley value:

$$v = \sum_{S \in \mathcal{N}} I^v(S) b'_S = \sum_{i \in \mathcal{N}} \Phi_i^{\text{Sh}}(v) b'_{\{i\}} + \sum_{|S| \neq 1} I^v(S) b'_S,$$

which implies

$$v \in \ker(\Phi^{\text{Sh}}) \iff v = \sum_{|S| \neq 1} I^v(S) b'_S$$

i.e.,

$$\ker(\Phi^{\text{Sh}}) = \left\{ \sum_{|S| \neq 1} \lambda_S b'_S \mid \lambda_S \in \mathbb{R} \right\}$$

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.
- ▶ Find b_1, \dots, b_k such that $\Phi(b_i) = e_i$ ($i = 1, \dots, k$).

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.
- ▶ Find b_1, \dots, b_k such that $\Phi(b_i) = e_i$ ($i = 1, \dots, k$).
- ▶ Then $\{b_1, \dots, b_k\}$ is a basis of $\Phi(\mathbb{R}^{\mathcal{N}})$, which can be completed by $\{b_{k+1}, \dots, b_{2^n}\}$ to form a basis of $\mathbb{R}^{\mathcal{N}}$.

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.
- ▶ Find b_1, \dots, b_k such that $\Phi(b_i) = e_i$ ($i = 1, \dots, k$).
- ▶ Then $\{b_1, \dots, b_k\}$ is a basis of $\Phi(\mathbb{R}^{\mathcal{N}})$, which can be completed by $\{b_{k+1}, \dots, b_{2^n}\}$ to form a basis of $\mathbb{R}^{\mathcal{N}}$.
- ▶ Denote by $\epsilon_1^{(j)}, \dots, \epsilon_k^{(j)}$ the coordinates of $\Phi(b_j)$ in the basis E , for $j = k + 1, \dots, 2^n$.

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.
- ▶ Find b_1, \dots, b_k such that $\Phi(b_i) = e_i$ ($i = 1, \dots, k$).
- ▶ Then $\{b_1, \dots, b_k\}$ is a basis of $\Phi(\mathbb{R}^{\mathcal{N}})$, which can be completed by $\{b_{k+1}, \dots, b_{2^n}\}$ to form a basis of $\mathbb{R}^{\mathcal{N}}$.
- ▶ Denote by $\epsilon_1^{(j)}, \dots, \epsilon_k^{(j)}$ the coordinates of $\Phi(b_j)$ in the basis E , for $j = k+1, \dots, 2^n$.
- ▶ Put $b_j^\Phi = b_j - \sum_{i=1}^k \epsilon_i^{(j)} b_i$ for $j = k+1, \dots, 2^n$.

The inverse problem: Solution 2

- ▶ Let $k = \dim \Phi(\mathbb{R}^{\mathcal{N}}) \leq n$ be the dimension of Φ , and select a basis $E = \{e_1, \dots, e_k\}$ of $\Phi(\mathbb{R}^{\mathcal{N}})$.
- ▶ Find b_1, \dots, b_k such that $\Phi(b_i) = e_i$ ($i = 1, \dots, k$).
- ▶ Then $\{b_1, \dots, b_k\}$ is a basis of $\Phi(\mathbb{R}^{\mathcal{N}})$, which can be completed by $\{b_{k+1}, \dots, b_{2^n}\}$ to form a basis of $\mathbb{R}^{\mathcal{N}}$.
- ▶ Denote by $\epsilon_1^{(j)}, \dots, \epsilon_k^{(j)}$ the coordinates of $\Phi(b_j)$ in the basis E , for $j = k+1, \dots, 2^n$.
- ▶ Put $b_j^\Phi = b_j - \sum_{i=1}^k \epsilon_i^{(j)} b_i$ for $j = k+1, \dots, 2^n$.

Theorem

Let $B^\Phi = \{b_1, \dots, b_k, b_{k+1}^\Phi, \dots, b_{2^n}^\Phi\}$. Then

- B^Φ is a basis for $\mathbb{R}^{\mathcal{N}}$.
- $B_0^\Phi = \{b_{k+1}^\Phi, \dots, b_{2^n}^\Phi\}$ is a basis for $\ker \Phi$.

Least square values

- ▶ A *least square value* Φ is given by the solution of a least square optimization problem

$$\min_{x \in \mathbb{R}^N} \sum_{S \in \mathcal{N}} \alpha_S (v(S) - x(S))^2 \quad \text{s.t.} \quad x(N) = v(N)$$

for given coefficients α_S , $S \in \mathcal{N}$, and the convention $x(S) = \sum_{i \in S} x_i$. Then $\Phi_i(v) = x_i^*$, $i \in N$.

Least square values

- ▶ A *least square value* Φ is given by the solution of a least square optimization problem

$$\min_{x \in \mathbb{R}^N} \sum_{S \in \mathcal{N}} \alpha_S (v(S) - x(S))^2 \quad \text{s.t.} \quad x(N) = v(N)$$

for given coefficients α_S , $S \in \mathcal{N}$, and the convention $x(S) = \sum_{i \in S} x_i$. Then $\Phi_i(v) = x_i^*$, $i \in N$.

- ▶ **Well-known fact 1:** the Banzhaf value is the solution of the above unweighted ($\alpha_S = 1, \forall S$) unconstrained problem (Hammer and Holzman 1987).

Least square values

- ▶ A *least square value* Φ is given by the solution of a least square optimization problem

$$\min_{x \in \mathbb{R}^N} \sum_{S \in \mathcal{N}} \alpha_S (v(S) - x(S))^2 \quad \text{s.t.} \quad x(N) = v(N)$$

for given coefficients α_S , $S \in \mathcal{N}$, and the convention $x(S) = \sum_{i \in S} x_i$. Then $\Phi_i(v) = x_i^*$, $i \in N$.

- ▶ Well-known fact 1: the Banzhaf value is the solution of the above unweighted ($\alpha_S = 1, \forall S$) unconstrained problem (Hammer and Holzman 1987).
- ▶ Well-known fact 2: the Shapley value is the solution of the above problem with

$$\alpha_S = \alpha_s = \frac{(n-2)!}{(s-1)!(n-1-s)!} \quad (s = |S|).$$

(Charnes et al., 1988)

Least square values

- ▶ It can be shown that the above problem reduces to

$$\min_{x \in \mathbb{R}^N} xQx^T - xc^T \quad \text{s.t.} \quad x1 = g(v)$$

with $q_{ij} = \sum_{S \ni i, j} \alpha_S$ and $c_i = \sum_{S \ni i} \alpha_S v(S)$. It has always a solution, which is unique iff Q is positive definite.

Least square values

- ▶ It can be shown that the above problem reduces to

$$\min_{x \in \mathbb{R}^N} xQx^T - xc^T \quad \text{s.t.} \quad x1 = g(v)$$

with $q_{ij} = \sum_{S \ni i, j} \alpha_S$ and $c_i = \sum_{S \ni i} \alpha_S v(S)$. It has always a solution, which is unique iff Q is positive definite.

- ▶ Q is said to be *regular* if $q_{ii} = q, \forall i$ and $q_{ij} = p$ for all $i \neq j$.

Least square values

- ▶ It can be shown that the above problem reduces to

$$\min_{x \in \mathbb{R}^N} xQx^T - xc^T \quad \text{s.t.} \quad x1 = g(v)$$

with $q_{ij} = \sum_{S \ni i, j} \alpha_S$ and $c_i = \sum_{S \ni i} \alpha_S v(S)$. It has always a solution, which is unique iff Q is positive definite.

- ▶ Q is said to be *regular* if $q_{ii} = q, \forall i$ and $q_{ij} = p$ for all $i \neq j$.
- ▶ **Fact:** Q regular is positive definite iff $q > p \geq 0$.

Least square values

- ▶ It can be shown that the above problem reduces to

$$\min_{x \in \mathbb{R}^N} xQx^T - xc^T \quad \text{s.t.} \quad x\mathbf{1} = g(v)$$

with $q_{ij} = \sum_{S \ni i, j} \alpha_S$ and $c_i = \sum_{S \ni i} \alpha_S v(S)$. It has always a solution, which is unique iff Q is positive definite.

- ▶ Q is said to be *regular* if $q_{ii} = q, \forall i$ and $q_{ij} = p$ for all $i \neq j$.
- ▶ **Fact:** Q regular is positive definite iff $q > p \geq 0$.

Theorem

If Q is regular and positive definite, the (unique) optimal solution x^* is given by:

$$\begin{aligned} z^* &= (2(q + (n-1)p)g - C)/n \quad (\text{with } C = c\mathbf{1}^T = \sum_{i \in N} c_i) \\ x_i^* &= (c_i + z^* - 2pg)/(2q - 2p) \quad (i \in N). \end{aligned}$$