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# Distributivity of implications over t-representable operations in interval-valued fuzzy sets theory

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# OUTLINE

- Motivation and historical background
- Basic definitions and preliminary results
- Main equation for t-representable t-norms
- Some results pertaining to functional equations
- Conclusion and further work

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In the classical logic we have the following tautology:

$$(p \wedge q) \mapsto r \equiv (p \mapsto r) \lor (q \mapsto r).$$

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$$(p \wedge q) \mapsto r \equiv (p \mapsto r) \vee (q \mapsto r).$$

If we consider a generalization of this formula in (classical) fuzzy logic, then we obtain the following functional equation

$$I(T(x,y),z) = S(I(x,z), I(y,z)), x, y, z \in [0,1], (1)$$

where

$$\begin{split} T\colon [0,1]^2 &\to [0,1] \text{ is some extension of classical conjunction (t-norm)} \\ S\colon [0,1]^2 &\to [0,1] \text{ is some extension of classical disjunction (t-conorm)} \\ I\colon [0,1]^2 &\to [0,1] \text{ is some extension of classical implication (fuzzy implication)} \end{split}$$

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W.E. Combs, J.E. Andrews (1998): Combinatorial rule explosion eliminated by a fuzzy rule configuration, *IEEE Trans. Fuzzy Systems* 6, 1–11 (1998) They refer to the left-hand side of this equivalence as an intersection rule configuration (IRC) and to its right-hand side as a union rule configuration (URC).

# **S.** Dick, A. Kandel (1999): Comments on "Combinatorial rule explosion eliminated by a fuzzy rule configuration", *IEEE Trans. Fuzzy Syst.* 7, 475–477:

"Future work on this issue will require an examination of the properties of various combinations of fuzzy unions, intersections and implications."

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J.M. Mendel, Q. Liang (1999): Comments on "Combinatorial rule explosion eliminated by a fuzzy rule configuration", *IEEE Trans. Fuzzy Syst.* 7, 369–371:

"We think that what this all means is that we have to look past the mathematics of IRC $\Leftrightarrow$ URC and inquire whether what we are doing when we replace IRC by URC makes sense."

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Aczél (1966): general solutions of the distributive equation

$$F(x,G(y,z))=G(F(x,z),F(y,z)),$$

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**E. Trillas & C. Alsina, (2002): On the Law**  $[p \land q \rightarrow r] = [(p \rightarrow r) \lor (q \rightarrow r)]$ **in Fuzzy Logic**, *IEEE Trans. Fuzzy Syst.* 10, 84–88. Investigations on the equation (1):

$$I(T(x,y),z)=S(I(x,z),I(y,z)), \qquad x,y,z\in [0,1],$$

in the case when T is a t-norm, S is a t-conorm and I is a fuzzy implication. In the case of

- R-implications generated from left-continuous t-norms
- S-implications

the equation (1) holds if and only if  $T = \min$  and  $S = \max$ .

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We can consider other distributive laws for the classical implication:

$$\begin{array}{l} (p \lor q) \mapsto r \equiv (p \mapsto r) \land (q \mapsto r) \\ p \mapsto (q \land r) \equiv (p \mapsto q) \land (p \mapsto r) \\ p \mapsto (q \lor r) \equiv (p \mapsto q) \lor (p \mapsto r) \end{array}$$

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All above equalities can be transformed to the functional equations of Pexider type:

$$\begin{split} I_1(T(x,y),z) &= S(I_2(x,z),I_3(y,z)) & \text{(D1)}\\ I_1(S(x,y),z) &= T(I_2(x,z),I_3(y,z)) & \text{(D2)}\\ I_1(x,T_1(y,z)) &= T_2(I_2(x,y),I_3(x,z)) & \text{(D3)}\\ I_1(x,S_1(y,z)) &= S_2(I_2(x,y),I_3(x,z)) & \text{(D4)} \end{split}$$

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**Baczyński (2001, 2002):** Eq. (D3) when  $T_1 = T_2$  is a strict t-norm

Jayaram & Rao (2004): Eqs. (D2) – (D4) for R-implications and S-implications. In almost all the cases the distributivity holds only when  $T_1 = T_2 = T = \min$  and  $S_1 = S_2 = S = \max$ 

**Ruiz-Aguilera & Torrens (2005, 2007):** Distributivity of different classes of fuzzy implications over different classes of uninorms

Qin & Zhao (2005): Distributive equations for idempotent uninorms and nullnorms

Baczyński & Jayaram (2007, 2008, 2010): Distributivity of fuzzy implications over continuous Archimedean t-norms and t-conorms

Drewniak & Rak (2009): Subdistributivity and superdistributivity of binary op.

Baczyński (2010): Distributivity of fuzzy implications over representable uninorms

Qin & Yang (2010): Distributivity of fuzzy implications over nilpotent t-norms

Baczyński & Qin (2011): Distributivity of fuzzy implications over continuous t-norms M. Baczyński, FSTA 2012 *First Prev Next Last Go Back Full Screen Close* Page 7

# MAIN GOAL

The distributivity equations in:

- Atanassov's intuitionistic fuzzy sets theory
- in interval-valued fuzzy sets theory.

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# THIS CONTRIBUTION

Solutions of the following distributive equation

$$\mathcal{I}(x, \mathcal{T}_1(y, z)) = \mathcal{T}_2(\mathcal{I}(x, y), \mathcal{I}(x, z))$$

for t-representable t-norms in interval-valued fuzzy sets theory.

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#### Definition 1 (Atanassov, 1999).

An (Atanassov's) intuitionistic fuzzy set A on X is a set

$$A = \{ (x, \mu_A(x), \nu_A(x)) : x \in X \},\$$

where  $\mu_A$ ,  $\nu_A \colon X \to [0,1]$  are called, respectively, the membership function and the non-membership function. Moreover, they satisfy the condition

$$\mu_A(x) + \nu_A(x) \le 1, \qquad x \in X.$$

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An (Atanassov's) intuitionistic fuzzy set A on X can be represented by the  $\mathcal{L}^*$ -fuzzy set A in the sense of Goguen given by

$$A: X \to L^*$$
  
  $x \mapsto (\mu_A(x), \nu_A(x)), \qquad x \in X,$ 

where  $\mathcal{L}^* = (L^*, \leq_{L^*})$  is the following complete lattice

$$L^* = \{ (x_1, x_2) \in [0, 1]^2 : x_1 + x_2 \le 1 \}$$
  
$$(x_1, x_2) \le_{L^*} (y_1, y_2) \iff x_1 \le y_1 \land x_2 \ge y_2$$

with the units  $0_{L^*} = (0, 1)$  and  $1_{L^*} = (1, 0)$ .

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Another extension of the fuzzy sets theory is interval-valued fuzzy sets theory introduced, independently, by **Sambuc (1975) & Gorzałczany (1987)**. We define  $\mathcal{L}^{I} = (L^{I}, \leq_{L^{I}})$ , where

 $L^{I} = \{ (x_{1}, x_{2}) \in [0, 1]^{2} : x_{1} \le x_{2} \}$  $(x_{1}, x_{2}) \le_{L^{I}} (y_{1}, y_{2}) \Longleftrightarrow x_{1} \le y_{1} \land x_{2} \le y_{2}$ 

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In the sequel, if  $x \in L^{I}$ , then we denote it by  $x = [x_{1}, x_{2}]$ .  $\mathcal{L}^{I}$  is a complete lattice with units  $0_{\mathcal{L}^{I}} = [0, 0]$  and  $1_{\mathcal{L}^{I}} = [1, 1]$ .

**Definition 2.** An interval-valued fuzzy set on X is a mapping  $A: X \to L^{I}$ .

An interval-valued fuzzy set can be seen as a  $\mathcal{L}^{I}$ -fuzzy set in the sense of Goguen.

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**Deschrijver & Kerre (2003)**: Atanassov's intuitionistic fuzzy sets can be seen as interval-valued fuzzy sets (and vice-versa).

In our talk we develop our investigations in the terms of  $\mathcal{L}^{I} = (L^{I}, \leq_{L^{I}})$ , since the main results are easier to obtain and to show.

**Definition 3.** Let  $\mathcal{L} = (L, \leq_L)$  be a complete lattice. An associative, commutative operation  $\mathcal{T} \colon L^2 \to L$  is called a t-norm on  $\mathcal{L}$  if it is increasing and  $1_{\mathcal{L}}$  is the neutral element of  $\mathcal{T}$ .

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#### T-norms on $\mathcal{L}^{I}$

T-norms on  $\mathcal{L}^{I}$  can be defined in many ways. In our talk we consider only the following special class of t-norms.

#### Definition 4.

A t-norm  $\mathcal{T}$  on  $\mathcal{L}^I$  is called t-representable if there exist t-norms  $T_1$  and  $T_2$  on  $([0,1],\leq)$  such that  $T_1 \leq T_2$  and

 $\mathcal{T}([x_1, x_2], [y_1, y_2]) = [T_1(x_1, y_1), T_2(x_2, y_2)], \qquad [x_1, x_2], [y_1, y_2] \in L^I.$ 

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It should be noted that not all t-norms on  $\mathcal{L}^{I}$  are t-representable.

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#### Definition 5 (Kitainik (1993); Fodor & Roubens (1994)).

Let  $\mathcal{L} = (L, \leq_L)$  be a complete lattice. A function  $\mathcal{I} \colon L^2 \to L$  is called a fuzzy implication on  $\mathcal{L}$  if

- it is decreasing with respect to the first variable,
- it is increasing with respect to the second variable
- it fulfills the following conditions:

$$\mathcal{I}(0_{\mathcal{L}}, 0_{\mathcal{L}}) = \mathcal{I}(1_{\mathcal{L}}, 1_{\mathcal{L}}) = 1_{\mathcal{L}}, \qquad \mathcal{I}(1_{\mathcal{L}}, 0_{\mathcal{L}}) = 0_{\mathcal{L}}.$$

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Directly from the above definition we can deduce that each implication  $\mathcal{I}$  on  $\mathcal{L}$  satisfies also the normality condition  $\mathcal{I}(0_{\mathcal{L}}, 1_{\mathcal{L}}) = 1_{\mathcal{L}}$ . Consequently, every implication restricted to the set  $\{0_{\mathcal{L}}, 1_{\mathcal{L}}\}^2$  coincides with the classical implication.

When  $\mathcal{L} = ([0, 1], \leq)$ , then  $\mathcal{I}$  is called a fuzzy implication,

When  $\mathcal{L} = \mathcal{L}^{I}$ , then  $\mathcal{I}$  is called an interval-valued fuzzy implication.

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#### Main equation

$$\mathcal{I}(x, \mathcal{T}_1(y, z)) = \mathcal{T}_2(\mathcal{I}(x, y), \mathcal{I}(x, z))$$

when t-norms  $\mathcal{T}_1 = (T_1, T_2)$  and  $\mathcal{T}_2 = (T_3, T_4)$  on  $\mathcal{L}^I$  are t-representable.

(2)

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when t-norms  $\mathcal{T}_1 = (T_1, T_2)$  and  $\mathcal{T}_2 = (T_3, T_4)$  on  $\mathcal{L}^I$  are t-representable.

Assume that projection mappings on  $\mathcal{L}^{I}$  are defined as the following:

$$pr_1([x_1, x_2]) = x_1, \qquad pr_2([x_1, x_2]) = x_2, \qquad \text{for } [x_1, x_2] \in L^I.$$

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At this situation our distributive equation has the following form

$$\begin{split} \mathcal{I}([x_1, x_2], &[T_1(y_1, z_1), T_2(y_2, z_2)]) \\ = &[T_3(pr_1(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_1(\mathcal{I}([x_1, x_2], [z_1, z_2]))), \\ &T_4(pr_2(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_2(\mathcal{I}([x_1, x_2], [z_1, z_2])))], \end{split}$$

for all  $[x_1, x_2], [y_1, y_2], [z_1, z_2] \in L^I$ .

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(2)

 $\begin{aligned} pr_1(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) &= T_3(pr_1(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_1(\mathcal{I}([x_1, x_2], [z_1, z_2]))), \\ pr_2(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) &= T_4(pr_2(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_2(\mathcal{I}([x_1, x_2], [z_1, z_2]))) \end{aligned}$ 

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Now, let us fix arbitrarily  $[x_1,x_2]\in L^I$  and define two functions  $L^I\rightarrow L^I$  by

$$g_{[x_1,x_2]}^1(\cdot) := pr_1 \circ \mathcal{I}([x_1,x_2],\cdot), \qquad g_{[x_1,x_2]}^2(\cdot) := pr_2 \circ \mathcal{I}([x_1,x_2],\cdot).$$

$$\begin{aligned} pr_1(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) \\ &= T_3(pr_1(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_1(\mathcal{I}([x_1, x_2], [z_1, z_2]))), \\ pr_2(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) \\ &= T_4(pr_2(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_2(\mathcal{I}([x_1, x_2], [z_1, z_2]))) \end{aligned}$$

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Then we get the following two equations

$$\begin{split} g^1_{[x_1,x_2]}([T_1(y_1,z_1),T_2(y_2,z_2)]) &= T_3(g^1_{[x_1,x_2]}([y_1,y_2]),g^1_{[x_1,x_2]}([z_1,z_2])),\\ g^2_{[x_1,x_2]}([T_1(y_1,z_1),T_2(y_2,z_2)]) &= T_4(g^2_{[x_1,x_2]}([y_1,y_2]),g^2_{[x_1,x_2]}([z_1,z_2])). \end{split}$$

$$\begin{aligned} pr_1(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) \\ &= T_3(pr_1(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_1(\mathcal{I}([x_1, x_2], [z_1, z_2]))), \\ pr_2(\mathcal{I}([x_1, x_2], [T_1(y_1, z_1), T_2(y_2, z_2)])) \\ &= T_4(pr_2(\mathcal{I}([x_1, x_2], [y_1, y_2])), pr_2(\mathcal{I}([x_1, x_2], [z_1, z_2]))) \end{aligned}$$

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$$\begin{split} g^1_{[x_1,x_2]}([T_1(y_1,z_1),T_2(y_2,z_2)]) &= T_3(g^1_{[x_1,x_2]}([y_1,y_2]),g^1_{[x_1,x_2]}([z_1,z_2])),\\ g^2_{[x_1,x_2]}([T_1(y_1,z_1),T_2(y_2,z_2)]) &= T_4(g^2_{[x_1,x_2]}([y_1,y_2]),g^2_{[x_1,x_2]}([z_1,z_2])). \end{split}$$

When  $T_1 = T_2 = T_3 = T_4$ , then in both cases we have the bisymmetry equation. The continuous and strictly increasing solutions are known even for domain  $L^I$ (Kocsis (2007): A bisymmetry equation on restricted domain). But in our investigation t-norms are not strictly increasing on the whole domain.

We have solved (almost completely) this problem for the case when  $T_1 = T_2$ and  $T_3 = T_4$  are continuous and Archimedean t-norms on unit interval. We have solved (almost completely) this problem for the case when  $T_1 = T_2$ and  $T_3 = T_4$  are continuous and Archimedean t-norms on unit interval.

**Theorem 1.** A function  $T: [0,1]^2 \rightarrow [0,1]$  is a nilpotent t-norm if and only if there exists a continuous, strictly decreasing function  $t: [0,1] \rightarrow [0,\infty)$  with t(1) = 0, which is uniquely determined up to a positive multiplicative constant, such that

 $T(x,y) = t^{-1}(\min(t(x) + t(y), t(0))), \qquad x, y \in [0,1].$ 

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We can transform our problem to the following equation (we deal only with  $g^1$ ):

$$g_{[x_1,x_2]}^1([t_1^{-1}(\min(t_1(y_1) + t_1(z_1), t_1(0))), t_1^{-1}(\min(t_1(y_2) + t_1(z_2), t_1(0)))]) = t_3^{-1}(\min(t_3(g_{[x_1,x_2]}^1([y_1,y_2])) + t_3(g_{[x_1,x_2]}^1([z_1,z_2])), t_3(0))).$$

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Hence

$$t_3 \circ g^1_{[x_1,x_2]}([t_1^{-1}(\min(t_1(y_1) + t_1(z_1), t_1(0))), t_1^{-1}(\min(t_1(y_2) + t_1(z_2), t_1(0)))]) \\= \min(t_3 \circ g^1_{[x_1,x_2]}([y_1,y_2]) + t_3 \circ g^1_{[x_1,x_2]}([z_1,z_2]), t_3(0)).$$

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We can transform our problem to the following equation (we deal only with  $g^1$ ):

$$g_{[x_1,x_2]}^1([t_1^{-1}(\min(t_1(y_1) + t_1(z_1), t_1(0))), t_1^{-1}(\min(t_1(y_2) + t_1(z_2), t_1(0)))]) = t_3^{-1}(\min(t_3(g_{[x_1,x_2]}^1([y_1, y_2])) + t_3(g_{[x_1,x_2]}^1([z_1, z_2])), t_3(0))).$$

Hence

$$t_3 \circ g^1_{[x_1,x_2]}([t_1^{-1}(\min(t_1(y_1) + t_1(z_1), t_1(0))), t_1^{-1}(\min(t_1(y_2) + t_1(z_2), t_1(0)))]) \\ = \min(t_3 \circ g^1_{[x_1,x_2]}([y_1,y_2]) + t_3 \circ g^1_{[x_1,x_2]}([z_1,z_2]), t_3(0)).$$

Let  $L^a = \{(u_1, u_2) \in [0, a]^2 : u_1 \ge u_2\}$ , for real a > 0. Let us put  $t_1(y_1) = u_1$ ,  $t_1(y_2) = u_2$ ,  $t_1(z_1) = v_1$  and  $t_1(z_2) = v_2$ .

$$[y_1, y_2], [z_1, z_2] \in L^I \Longrightarrow (u_1, u_2), (v_1, v_2) \in L^{t_1(0)}$$

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If we put

$$f_{[x_1,x_2]}(u,v) := t_3 \circ pr_1 \circ \mathcal{I}([x_1,x_2],[t_1^{-1}(u),t_1^{-1}(v)]),$$

where  $u, v \in [0, t_1(0)], u \ge v$ , then we get the following functional equation

$$f_{[x_1,x_2]}(\min(u_1+v_1,t_1(0)),\min(u_2+v_2,t_1(0)))$$
  
= min(f\_{[x\_1,x\_2]}(u\_1,u\_2) + f\_{[x\_1,x\_2]}(v\_1,v\_2),t\_3(0)),

satisfied for all  $(u_1, u_2), (v_1, v_2) \in L^{t_1(0)}$ . Of course function  $f_{[x_1, x_2]} \colon L^{t_1(0)} \to [0, t_3(0)]$  is unknown above.

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In a same way we can repeat all the above calculations, but for the function  $g^2$ , to obtain the following functional equation

$$f^{[x_1,x_2]}(\min(u_1+v_1,t_1(0)),\min(u_2+v_2,t_1(0))) = \min(f^{[x_1,x_2]}(u_1,u_2) + f^{[x_1,x_2]}(v_1,v_2),t_3(0)),$$

satisfied for all  $(u_1, u_2), (v_1, v_2) \in L^{t_1(0)}$ , where

$$f^{[x_1,x_2]}(u,v) := t_3 \circ pr_2 \circ \mathcal{I}([x_1,x_2],[t_1^{-1}(u),t_1^{-1}(v)])$$

is an unknown function.

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#### Results pertaining to functional equations

 $L^{\infty} = \{ (u_1, u_2) \in [0, \infty]^2 \mid u_1 \ge u_2 \}$  $L^a = \{ (u_1, u_2) \in [0, a]^2 \mid u_1 \ge u_2 \}$ 

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Solutions when  $T_1 = T_2$  and  $T_3 = T_4$  are strict t-norms

$$f(u_1 + v_1, u_2 + v_2) = f(u_1, u_2) + f(v_1, v_2)$$

 $f \colon L^{\infty} \to [0,\infty]$  is an unknown function.

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Solutions when  $T_1 = T_2$  and  $T_3 = T_4$  are nilpotent t-norms

$$h(\min(u_1 + v_1, a), \min(u_2 + v_2, a)) = \min(h(u_1, u_2) + h(v_1, v_2), b)$$
(4)

 $h \colon L^a \to [0, b]$  is an unknown function.

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Solutions when  $T_1 = T_2$  is a nilpotent t-norm and  $T_3 = T_4$  is a strict t-norm

$$g(\min(u_1 + v_1, a), \min(u_2 + v_2, a)) = g(u_1, u_2) + g(v_1, v_2)$$

$$g: L^a \to [0, \infty] \text{ is an unknown function.}$$
(5)

Solutions when  $T_1 = T_2$  is a nilpotent t-norm and  $T_3 = T_4$  is a strict t-norm

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$$g: L^a \to [0, \infty] \text{ is an unknown function.}$$
(5)

Solutions when  $T_1 = T_2$  is a strict t-norm and  $T_3 = T_4$  is a nilptent t-norm

$$k(u_1 + v_1, u_2 + v_2) = \min(k(u_1, u_2) + k(v_1, v_2), b)$$
(6)

 $k \colon L^{\infty} \to [0, b]$  is an unknown function.

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#### Proposition 1 (Baczyński, Jayaram (2009)).

Fix real a, b > 0. For a function  $f: [0, a] \rightarrow [0, b]$  the following statements are equivalent:

(i) f satisfies the functional equation

$$f(\min(x+y,a)) = \min(f(x) + f(y), b), \qquad x, y \in [0,a]$$

(ii) Either f = 0, or f = b, or  $f(x) = \begin{cases} 0, & \text{if } x = 0, \\ b, & \text{if } x > 0, \end{cases}$ , or there exists a unique constant  $c \in \left[\frac{b}{a}, \infty\right)$  such that  $f(x) = \min(cx, b)$ , for all  $x \in [0, a]$ .

# Main results

$$\mathcal{I}(x, \mathcal{T}_1(y, z)) = \mathcal{T}_2(\mathcal{I}(x, y), \mathcal{I}(x, z))$$

Using this method we are able to solve our main equation when t-norms  $\mathcal{T}_1 = (T_1, T_2)$ and  $\mathcal{T}_2 = (T_3, T_4)$  on  $\mathcal{L}^I$  are t-representable and such that  $T_1 = T_2$  and  $T_3 = T_4$  are continuous and Archmidean t-norms.

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# FURTHER WORK IN THIS TOPIC

- Detailed description of all correct solutions
- Other distributive equations on  $\mathcal{L}^{I}$  for t-representable operations
- Other classes of t-norms
- Possible applications

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# Thank You for the attention!

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